



www.pingdsp.com

3DSS-iDX *Integrated INS Shallow Water Mapping/Imaging System*

- 3DSS-DX Sonar
- integrated AML Sound Velocity Sensor
- integrated INS (SBG IMU and Septentrio GNSS)
- ultra-compact and portable

SUPERIOR SHALLOW WATER HYDROGRAPHY

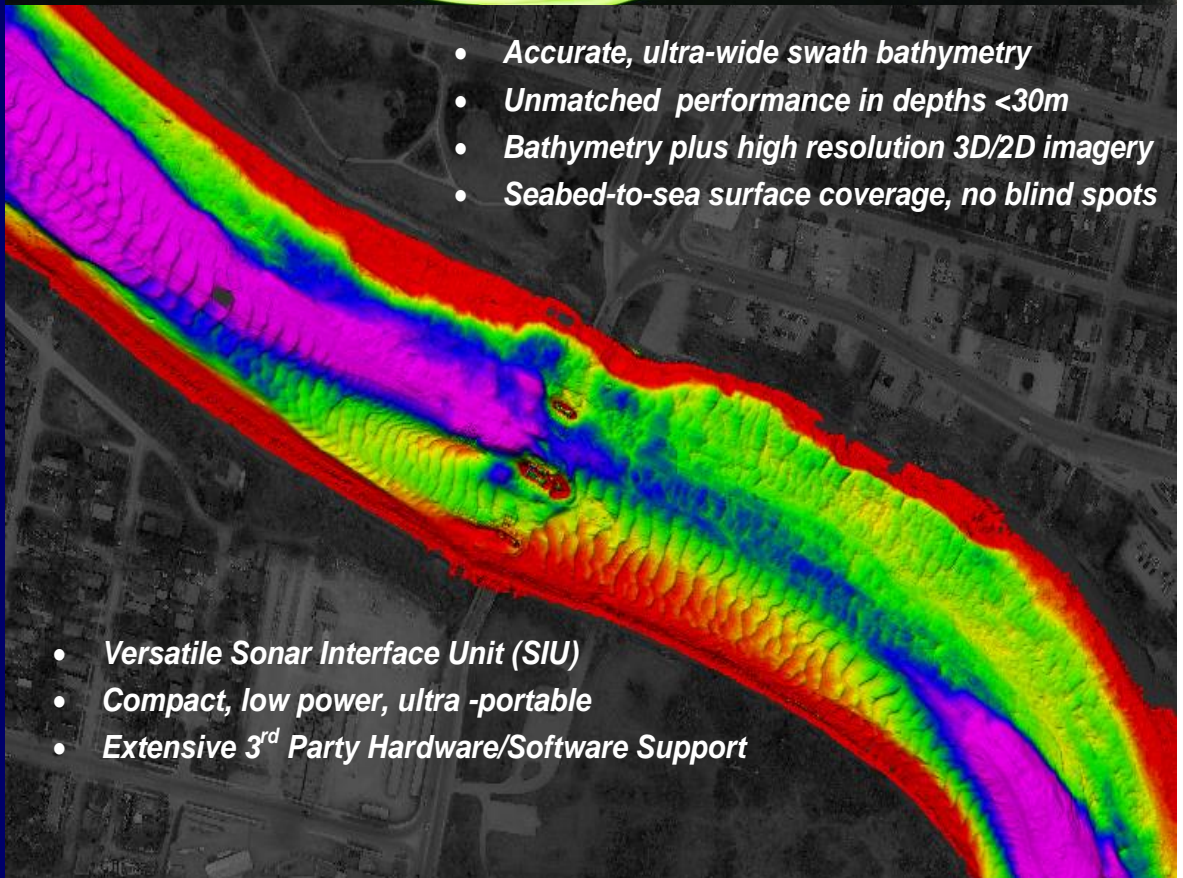
Accurate, high resolution, ultra-wide swath echo-sounding and 3D/2D imagery, with integrated real-time surface sound velocity, high accuracy INS position / attitude and optional RTK, PPK, PPP provide the best available hydrographic survey and imaging performance in shallow water.

SIMULTANEOUS REAL-TIME 3D IMAGERY

Geometrically correct, co-located 3D Sidescan imagery augments bathymetry and extends 2D sidescan resolution to three dimensions. **3DSS** real-time 3D software displays, captures and allows accurate measurement in three dimensions of features on the seabed and in the water-column including pipes, cables, pilings, wrecks, subsea structures hazards, ecological habitats, and other features not well defined in bathymetry or 2D sidescan.

COMPACT, ULTRA-PORTABLE, VERSATILE

A versatile Sonar Interface Unit provides ultra-portable, easy turnkey operation with just a laptop and a battery on small boats, USV's, and dedicated survey launches.



- *Accurate, ultra-wide swath bathymetry*
- *Unmatched performance in depths <30m*
- *Bathymetry plus high resolution 3D/2D imagery*
- *Seabed-to-sea surface coverage, no blind spots*

- *Versatile Sonar Interface Unit (SIU)*
- *Compact, low power, ultra -portable*
- *Extensive 3rd Party Hardware/Software Support*



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For more information please contact Ping DSP Inc. at: info@pingdsp.com

PATENTED ARRAY SIGNAL PROCESSING TECHNOLOGY

3DSS-iDX incorporates a patented signal processing methodology that extends the single angle-of-arrival principle used in interferometric systems to accommodate multiple simultaneous backscatter arrivals. When combined with the **3DSS-iDX** Multibeam Echo-Sounder Signal Processing Engine, the result is unsurpassed resolution and bathymetric accuracy over swath widths that can exceed 14 times water depth.

SOFTSONAR™ TECHNOLOGY

At the heart of the **3DSS-iDX** sonar is Ping DSP's state-of-the-art **SoftSonar™** electronics technology with ultra-low noise, wide dynamic range receivers, state-of-the-art acoustic transducer arrays, Gigabit Ethernet, easy-to-use software interface, and integrated support for a wide range of third party survey software and hardware.

BROAD APPLICATION

- Coastal Hydrographic survey
- River and Lake surveys
- Dredge surveys
- Tailing Pond surveys
- Subsea structure surveying
- Search and localization
- Benthic habitat mapping
- Underwater archaeology

3DSS-iDX Sonar Specifications¹

Sonar Configurations

| Model | Application | SVS | IMU | GNSS |
|---------------|--|-------------|---------------------|-------------------------|
| 3DSS-iDX-BASE | Hydrography + 3D/2D Sidescan - 0.05° IMU, ext GNSS | AML Micro-X | SBG Ellipse3 | External |
| 3DSS-iDX-FULL | Turnkey Hydrography + 3D/2D Sidescan - 0.05° IMU | AML Micro-X | SBG Ellipse3 | Septentrio AsteRx-m3 Fg |
| 3DSS-iDX-PRO | Turnkey Hydrography + 3D/2D Sidescan - 0.02° IMU | AML Micro-X | SBG Navsight Ekinox | Septentrio AsteRx-m3 Fg |

Sonar Specifications

| | | | |
|------------------------------|-----------------|---------------------------------|-------------|
| Operating Frequency | 450 kHz | Mech. Transducer Tilt (fixed) | 20° |
| Transmit Waveforms | CW, Broadband | Electronic Transmit Tilt | -45° to 45° |
| Pulse Lengths | 10 – 200 cycles | Max. Ping Rep. Rate | ~45 Hz |
| Horizontal Beamwidth (2 way) | 0.4° | Vertical Beamwidth (selectable) | 19° - 125° |

2D Sidescan (2D Imagery) Specifications

| | |
|------------------------|---|
| Data Output | Range and Amplitude |
| 2D Imaging Swath Width | 10 to 20 times sonar altitude, varies with sound velocity profile, geometry and seabed type |
| Max Range | 200m per side |
| Max Range Resolution | 1.67cm |

3D Sidescan (3D Imagery) Specifications

| | |
|-------------------------------|--|
| Data Output | Range, Angle, and Amplitude |
| 3D Imaging Swath Width | 8 to 14 times sonar altitude, varies with sound velocity profile, geometry and seabed type |
| Max 3D Imaging Range per Side | 120m per side |
| Max Resolution | 1.67cm |

Bathymetry Specifications

| | |
|-----------------------------|--|
| Data Output | Sounding Range, Angle, and Amplitude |
| Bathymetry Swath Width | 8 to 16 times sonar altitude, varies with sound velocity profile, geometry and seabed type |
| Max Bathymetry Range | 120m per side |
| Min. Sounding Depth | 0.5m |
| Max. Sounding Depth | 75m (reduced swath width) |
| Sounding Accuracy | Exceeds IHO Special Order, meets or exceeds Dutch Norm 1A and Canadian Exclusive Order |
| Multibeam Eq. Mode Settings | Beamwidth (0.25°-5°), Sector (90°-220°), Beams (3-1024), Mode (Equidistant, Equiangle, Hybrid) |
| Legacy Mode Settings | Bin Count (3-1440), Bin Width (5cm – 200cm) |

Integrated Sensor Specifications

| | | |
|--------------------------|---|---|
| SVS (-BASE, -FULL, -PRO) | AML MicroX ² | 1375 – 1600m/s SV range, 20ms resp, 0.025m/s accuracy |
| IMU (-BASE, -FULL) | IMU SBG Ellipse3 ³ | pitch,roll 0.05°(RTK), hdg 0.2°(2m baseline), heave 5cm |
| IMU (-PRO) | SBG Navsight Marine Ekinox ³ | pitch,roll 0.02°(RTK), hdg 0.08°(2m baseline), heave 2cm |
| GNSS (-FULL, -PRO) | Septentrio AsterRx-m3 Fg ⁴ | dual recvr., GPS, GLONASS, Galileo, BeiDou, QZSS, SBAS, L-band Rx, fully unlocked for RTK, PPK, PPP, 0.6/1cm horiz/vert. accuracy (RTK) |

Interface Specifications

| | |
|--|--|
| Control Input / Data Output | Gigabit Ethernet, sonar software provides control GUI and TCP data server |
| Time Reference | Time aligned to GNSS time |
| Additional Communication Ports | RS-232 or Ethernet, for external MRU, GNSS or INS, |
| Additional Inputs | PPS (SMA), Ext.Trigger (SMA) |
| Computer Requirements | PC (Quad Core, 16GB, Discrete GPU (e.g. Nvidia), MS Windows 7,8,10,11 (64 bit) |
| 3 rd Party Software Support | Hypack, SonarWiz, QINSy, PDS, BeamWorx, EIVA, Caris HIPS/SIPS |

Physical Specifications

| | |
|---------------------------------|---|
| Voltage Requirements | 12-28 VDC |
| Power Consumption | 25W (-BASE), 28W (-FULL, -PRO) |
| Sonar Head Dimensions | 61 cm (24") long x 9.8cm (3.88") diameter |
| Sonar Head Weight in Air, Water | 8.5 kg (18.7 lbs), 5 kg (11 lbs) |
| Sonar Interface Unit Dimensions | 25.5cm (10.04") wide x 15.5cm (6.10") deep x 5.8cm (2.28") tall |
| Pole Mount Adapter Diameter | 1.49" (fits standard thickwall 1.5" I.D. Aluminum pipe), Flange mount adapter also included |
| Ambient Operating Temp. | -5° C – 45° C |
| Depth Rating | 10 m |

Notes:

¹ Specifications subject to change without notice.

² See www.amloceanographic.com for complete specifications.

³ Specifications given for integrated 3DSS-INS operation and RTK corrections, see www.sbg-systems.com for full specifications.

⁴ See www.septentrio.com for complete specifications.